

1 **DESCRIPTION**

FINS is an Omron protocol which can be used by a PLC program to transfer data and perform other services with a remote PLC connected on an Ethernet Network.

The FINS protocol can be used by remote devices such a FieldServer to transfer data and perform other services.

The protocol uses the Ethernet protocol called UDP to carry the FINS messages back and forth. The UDP protocol is not connection based and reliability is achieved by using confirmation messages.

This Ethernet Driver can be used to transfer data to and from the Nodes supporting FINS communications.

By default driver uses Ethernet port 9600. This parameter is configurable.

The Driver can be configured as a Client or a Server.

As a Client: This driver reads and writes data to Server Nodes. Server nodes should be FINS capable and be configured to communicate over FINS.

As a Server: Driver responses to read requests and updated FieldServer Data Arrays with data from client.

FieldServer Mode	Nodes	Comments		
Client	126	Omron limit the set of permitted nodes to 126. They are numbered 1 to 126 corresponding to the last byte of the remote node IP address.		
Server	20	The FieldServer can emulate a maximum of 20 Omron FINS servers.		

2 FORMAL DRIVER TYPE

Ethernet

Client or Server

3 COMPATIBILITY MATRIX

FieldServer Model	Compatible with this driver
FS-x2010	Yes
FS-x2011	Yes
FS-x40	Yes
FS-x30	Yes
QuickServer FS-QS-1010	No
QuickServer FS-QS-1011	No
QuickServer FS-QS-1210	Yes
QuickServer FS-QS-1211	Yes
ProtoCessor FPC-FO2	Yes
ProtoCessor FPC-FD2	Yes



4 CONNECTION INFORMATION

Connection type:EthernetEthernet Speeds Supported10Base-T, 100Base-T¹

5 PLC TYPES SUPPORTED

PLC Туре	Vendor	Protocol
CS1/CJ1 Series	Omron	FINS

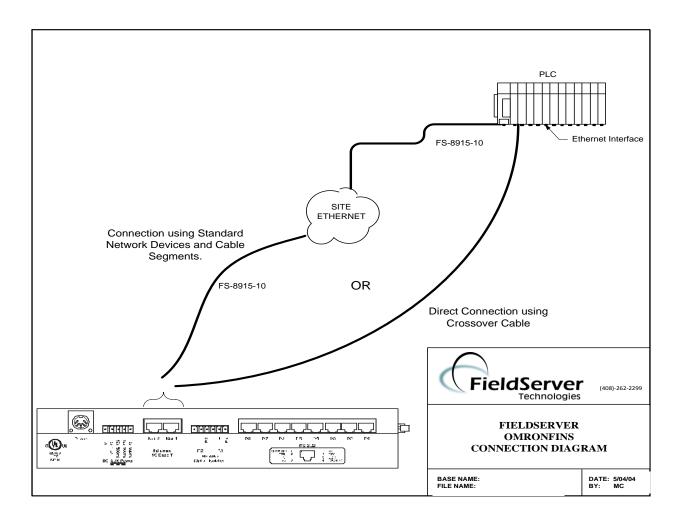
6 DEVICES TESTED

Device	Tested (FACTORY, SITE)
CJ1 Omron PLC	Factory

¹ Not all FieldServer models support 100BaseT. Consult the appropriate instruction manual for details of the Ethernet speed supported by specific hardware.



CONNECTION CONFIGURATIONS



7.1 Connection Notes

Target device may be from CS or CJ series with Ethernet port 10Base-T or 100Base-T capable as appropriate. Consult Instruction manual for further information.



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COMMUNICATIONS FUNCTIONS - SUPPORTED FUNCTIONS AT A GLANCE:

8.1 Supported FINS Command Set

PLC Type	Memory Type	Command name	Description	Device Data Type	Format	
		MEMORY AREA	MEMORY AREA Read the contents of consecutive I/O			
		READ	memory area words.	WR		
	I/O Memory			HR	Word	
	I/O Memory	MEMORY AREA	Writes the contents of consecutive I/O	AR	woru	
		WRITE	memory area words.	DM		
				EM		
	Operating Mode Changes	RUN	Changes the CPU Unit's operating			
			mode to RUN or MONITOR.	-	-	
		STOP	Changes the CPU Unit's operating			
CS1/CJ1		5101	mode to PROGRAM			
Series		CLOCK READ	Reads the present year, month, date,			
	Time Data		minute, second, and day of the week.	-		
	Access	Access		Changes the present year, month,	-	-
-		CLOCK WRITE	date, minute, second, or day of the			
			week.			
		CPU UNIT STATUS READ	Reads CPU status, operating mode,			
			other error messages and any text	-	-	
	Status Reading		message.			
		CYCLE TIME	Reads the CPU average, maximum and	-	-	
		READ	minimum cycle time.			



8.2 PLC status to execute commands

PLC Type	Memory Type	Command name	Run Mode	Monitor Mode	Program Mode	Access right ²	UM Read Protection ³	DIP UM Protection*** ⁴
		MEMORY AREA READ	ОК	ОК	ОК	ОК	ОК	ОК
	I/O Memory	MEMORY AREA WRITE	ОК	ОК	ОК	ОК	ОК	ОК
	Operating Mode Changes	RUN	ОК	ОК	ОК	Disabled	ОК	ОК
CC4 /C14		STOP	ОК	ОК	ОК	Disabled	ОК	ОК
CS1/CJ1 Series	Time Data	CLOCK READ	ОК	ОК	ОК	ОК	ОК	ОК
Series	Access	CLOCK WRITE	ОК	ОК	ОК	Disabled	ОК	ОК
	Status Reading	CPU UNIT STATUS READ	ОК	ОК	ОК	ОК	ОК	ОК
		CYCLE TIME READ	ОК	ОК	Disabled	ОК	ок	ОК

² Access Right at Other Device: The Access right at other device column tells whether the CPU Unit can or cannot receive a command when another device has the access right to the CPU Unit.

³ **UM Read Protection:** The UM read protection column tells whether the CPU Unit can or cannot receive the command when UM (user memory) is protected from a Peripheral Device.

⁴ **DIP Switch UM Protection:** The DIP switch UM protection column tells whether the CPU Unit can or cannot receive a command when UM is write-protected by turning ON pin 1 of the DIP switch on the CPU Unit's front panel.



8.3 Unsupported FINS commands

Memory Type	Commands	Description				
	PARAMETER AREA READ					
De versite et aus	PARAMETER AREA WRITE	Read, Write and Clear of Parameters like PLC Setup Area, CPU Bus Unit Setup Area etc				
Parameter Area	PARAMETER AREA FILL					
	(CLEAR)					
	PROGRAM AREA READ	Deed Write and Clean memory for particular Dramary in				
Program Area	PROGRAM AREA WRITE	Read, Write and Clear memory for particular Program in PLC.				
	PROGRAM AREA CLEAR					
Machine	CPU UNIT DATA READ	Reads CPU information (Model, Bus unit configuration				
Configuration Area	CONNECTION DATA READ	etc)				
Message Display Area	MESSAGE READ/CLEAR	Reads and Clears messages				
	ACCESS RIGHT ACQUIRE					
Assess Diabte Area	ACCESS RIGHT FORCED					
Access Rights Area	ACQUIRE	Acquiring and releasing Access right.				
	ACCESS RIGHT RELEASE					
	ERROR CLEAR					
Error Log area	ERROR LOG READ	Reads and Clear error messages or error log.				
EITOI LUg alea	ERROR LOG POINTER	Reads and clear error messages or error log.				
	CLEAR					
	FILE NAME READ					
	SINGLE FILE READ					
	SINGLE FILE WRITE					
	FILE MEMORY FORMAT					
	FILE DELETE					
	FILE COPY					
	FILE NAME CHANGE					
File Memory Area	MEMORY AREA-FILE	File operations				
	TRANSFER					
	PARAMETER AREA-FILE					
	TRANSFER					
	PROGRAM AREA-FILE					
	TRANSFER					
	CREATE/DELETE	7				
	DIRECTORY					
	FORCED SET/RESET					
Debugging Area	FORCED SET/RESET	Forcefully sets-resets bits				
	CANCEL					

*Note: FieldServer is a data transfer device, and as such, programming messages are not required



8.4 Unsupported Devices or Protocol Options

Device / Option	Details
CV Series	CV series PLC's or Ethernet Units (Cannot poll the Ethernet unit itself).
Socket Services.	This is an Omron protocol option that can be used to transfer data between Omron / other device . The Socket Services protocol is different from the FINS protocol and is not supported.